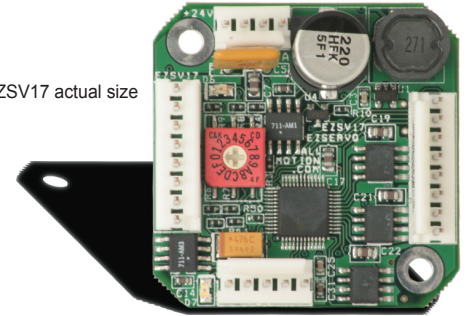


General Specifications

Supply Input	20V to 40V 2A <i>Examples:</i> Digikey part 285-1820 or 1470-1015
Dimensions	1.6" x 1.6" (40mm x 40mm) square, 0.6" (15.24mm) thick
Operating Modes	PC controlled or standalone. Position, velocity, and torque.
PC Control	Can control up to 16 drives daisy chained together.
Communications protocol	RS485. Can convert to RS232/USB with appropriate converters.
Control protocol	Compatible with devices that use the Cervo DT or OEM protocol. Can use EZCommander™ Windows application or serial terminal program such as HyperTerminal to issue commands.
Motor compatibility	Accommodates most 2" and smaller DC brush or brushless servo motors without tuning. Best performance is with motor rated at about 1/2 of supply voltage. Outputs short protected.
Mating Connectors	AMP MTA 100 series. Recommended tool: Digikey part A9982, or better Digikey parts A2031 + A1998. (See Application Note 131021 for non-standard connector options.)
I/O Interface	Accepts 2 opto-electronic and two mechanical switch inputs, or 4 mechanical switch inputs. Also ADC and encoder inputs. Signal Levels: <0.8V Vlow; >2V Vhigh (TTL compatible) Optical switch specifications: Transistor optical switch with IC> 1 mA @ IF=20mA. <i>Examples:</i> OPTEK part OPB841W55 or Digikey part 365-1103-ND (prewired); Honeywell HOA1870-33 (prewired)
Encoder interface	Primary and secondary quadrature encoders, max. freq. 4 MHz
Operating Temperature	-20 to 85 °C PCB copper temperature
Relative Humidity	10% to 90% non condensing (operating and storage)

Model EZSV17 actual size



HALL SENSOR & MOTOR CONNECTOR

Mating Connector: AMP MTA 100 series 8 pin, 22 GA, part 3-643813-8
Digikey part A31111-ND

Pin	Name	Notes
1	Hall sensor A	AllMotion will provide assistance determining correct hookup
2	Hall sensor B	
3	Hall sensor C	
4	+15V Hall sensor power	If +5V needed, use encoder power.
5	Ground	Ground for Hall sensors
6	Phase A driver (BLDC) Motor+ (brush DC)	2A peak PWM
7	Phase B driver (BLDC) Not used (brush DC)	2A peak PWM
8	Phase C driver (BLDC) Motor- (brush DC)	2A peak PWM

POWER AND COMMUNICATION CONNECTOR

Mating connector: AMP MTA 100 series 4 pin, 22GA, part 3-643813-4
Digikey part A31108-ND

Pin	Function
1	V+ (external supply) +20V to 40V
2	GROUND
3	RS485 B
4	RS485 A

Key Features

- Single 4-wire bus linking up to 16 drives
- 2A BLDC or DC brush motor drivers, short protected
- Operates from 20V to 40V.
- RS232, RS485, or USB-based control communications
- Optional standalone operation with no connection to PC
- On-board EEPROM for user program storage
- Homes to opto or encoder index with single command.
- Execution halt/branch pending switch closure
- ADC inputs, halt/branch to ADC value
- Position, velocity, and torque modes. Velocity mode possible with only Hall sensor feedback.
- Quadrature encoder-based feedback for position mode
- Step & Direction mode, 4MHz step frequency
- Secondary encoder mode
- 4MHz max encoder frequency
- Prewired for optoswitch inputs
- Cervo DT or OEM protocol compatible
- Fully programmable ramps and speeds
- Switch-selectable device address
- Software-settable maximum currents

Ordering Information

Name	Order Number
EZSV17 Servo Drive.....	EZSV17
RS232 to 485 Converter (option).....	RS485
USB to 485 Converter (option).....	USB485

I/O CONNECTOR

Mating Connector: AMP MTA 100 series 8 pin, 26 GA, part 3-643815-8
Digikey part A31030-ND

Pin	Name	Notes
1	A/D in #2, secondary encoder Chan B, or Direct input	Includes 10k Ω pullup to 3.3V.
2	A/D in #1, secondary encoder Chan A, or Step input	Includes 10k Ω pullup to 3.3V.
3	LED Drive #2	Includes series 200 Ω resistor to 5V.
4	A/D in #4, secondary encoder Index, or Upper Limit input	Includes 10k Ω pullup to 3.3V.
5	Ground	Common input ground
6	LED Drive #1	Includes series 200 Ω resistor to 5V.
7	A/D in #3 or Home/Lower Limit input	Includes 10k Ω pullup to 3.3V.
8	Ground	Common input ground

ENCODER CONNECTOR

Mating Connector: AMP MTA 100 series 5 pin, 26 GA, part 3-643815-5
Digikey part A31027-ND

Pin	Name	Notes	Pin	Name	Notes
1	Ground	Ground for primary encoder	4	+5V (V+)	Power to encoder; also use for Hall sensors requiring +5V
2	Index	Input from primary encoder	5	Chan B	Input from primary encoder
3	Chan A	Input from primary encoder			

Mechanical Specifications

